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A dynamic location problem with maximum decreasing capacities

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Abstract In this paper a capacitated dynamic location problem with opening, closure and reopening of facilities is formulated and a primal-dual heuristic that can solve this problem is described. The problem formulated considers the situation where a facility is open (or reopens) with a certain maximum capacity that decreases as clients are assigned to that facility during its operating periods. This problem is *NP*-hard. Computational results are presented and discussed.

Keywords Dynamic location problems · Heuristics

JEL Classification C61

1 Introduction

Consider a network with a set \mathcal{N} of nodes and a set \mathcal{A} of arcs. Set \mathcal{N} can be divided in two disjoint subsets $\mathcal{N}1$ and $\mathcal{N}2$. Nodes in $\mathcal{N}1$ are characterized by having a given

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demand. Nodes in \mathcal{N}_2 can, potentially, be suppliers. They are characterized by having maximum limits on the demand they can serve. There is a fixed cost incurred by fixing the capacity of a supplier in a value greater than zero. There are also costs incurred by satisfying the demand of a node in \mathcal{N}_1 using the capacity of a node in \mathcal{N}_2 . The objective is to decide which nodes in \mathcal{N}_2 will be used as suppliers and which arcs in \mathcal{A} will be used to satisfy the demand of all nodes in \mathcal{N}_1 , minimizing both fixed and assignment costs. As it is easily seen, this problem can be formulated as a capacitated location problem. Now imagine that the costs associated with arcs in \mathcal{A} can change over time, or even that the set \mathcal{A} itself can change over time (by insertion or deletion of arcs). It is also possible to imagine that the demand of nodes in \mathcal{N}_1 is time dependent. In this case, it is straightforward to conclude that the possibility of modifying the network design during the planning horizon should be considered. This means that there can exist nodes in \mathcal{N}_2 that are suppliers at time period t but not at $t + 1$ or $t - 1$, or arcs that are used in one time period and not in the next one or at the previous one. This dynamic version of the problem can be formulated as a dynamic location problem that allows the reconfiguration of suppliers more than once during the planning horizon.

The problem studied in this paper has two important characteristics that distinguish it from the previous work done in this area: it is a capacitated dynamic location problem that considers the possibility of reconfiguring one location more than once during the planning horizon. This means that a facility can be open, closed and reopen more than once, which increases the flexibility of the model. Differentiation between the opening and the reopening of a facility is convenient because it allows the differentiation of the corresponding fixed costs (that can be clearly different). The model proposed also consider the existence of closing costs which, most of the times, cannot be ignored. Moreover it considers a different type of capacity restrictions: the existence of an initial maximum capacity that decreases as the facility serves clients. These kind of restrictions appear, for instance, when locating sanitary landfills that have a maximum capacity when are opened that diminishes as the solid waste is disposed.

There are several references in the literature that deal with capacitated location problems (see, for instance, [Cornuejols et al. 1991](#); [Sridharan 1995](#)). It is more difficult to find references to the dynamic capacitated location problem than to the static version of the problem. Most of the references consider maximum capacity restrictions (see, for instance, [Van Roy and Erlenkotter 1982](#); [Saldanha da Gama 2002](#); [Saldanha da Gama and Captivo 2002](#); [Dias et al. 2006, 2007](#)), different from the ones considered in this paper.

The primal-dual heuristic developed here is based on the work of [Erlenkotter \(1978\)](#), [Van Roy and Erlenkotter \(1982\)](#) and [Guignard and Spielberg \(1979\)](#). This heuristic is also an extension of the previous work done by the authors [Dias et al. \(2006\)](#) considering a different kind of capacity restrictions. It builds a pair of primal and dual solutions, trying to force the complementary conditions to be fulfilled.

In the next two sections the problem addressed is formulated, the corresponding linear dual problem is presented and the primal-dual heuristic is described. In Sect. 4 computational experiments are described and the results shown, in Sect. 5 some final comments are made and future work directions are pointed out.

2 Dynamic location problem with maximum decreasing capacity constraints

Consider the following notation:

$J = \{1, \dots, i, \dots, n\}$ set of indices corresponding to the clients' locations;

$I = \{1, \dots, j, \dots, m\}$ set of indices corresponding to facilities' possible locations;

T = number of time periods considered in the planning horizon ($1 \leq t \leq \xi \leq T$);

c_{ij}^t = cost of fully assigning client j to facility i in period t ;

FA_{it}^ξ = fixed cost of opening a facility i at the beginning of period t , and closing it at the end of period ξ (the facility will be in operation from the beginning of t to the end of ξ);

FR_{it}^ξ = fixed cost of reopening a facility i at the beginning of period t , and closing it at the end of period ξ (the facility will be in operation from the beginning of t to the end of ξ);

d_j^t = demand of client j at period t ;

Q_i = maximum capacity of the facility located at i , at the time of (re) opening;

and let us define the variables:

$$a_{it}^\xi = \begin{cases} 1 & \text{if facility } i \text{ is opened at the beginning of period } t \\ & \text{and stays open until the end of period } \xi \\ 0 & \text{otherwise} \end{cases}$$

$$r_{it}^\xi = \begin{cases} 1 & \text{if facility } i \text{ is reopened at the beginning} \\ & \text{of period } t \text{ and stays open until the end} \\ & \text{of period } \xi \\ 0 & \text{otherwise} \end{cases}, t > 1$$

x_{ij}^t = fraction of customer j 's demand that is served by facility i during period t .

Consider a situation where a service can be opened (or reopened) with a certain maximum capacity. As long as this facility serves clients' demand, its capacity decreases. Examples of facilities with this kind of behavior can be found, for instance, in sanitary landfills. When these facilities are opened, they can receive a maximum quantity of solid waste. This maximum capacity decreases during the life-period of the sanitary landfill, as it receives solid waste.

The dynamic location problem with maximum decreasing capacities that allows facilities to open, close and reopen more than once during the planning horizon will be formulated as DC-DLPOCR:

DC-DLPOCR

$$\text{Min} \sum_t \sum_i \sum_j c_{ij}^t x_{ij}^t + \sum_t \sum_i \sum_{\xi=t}^T FA_{it}^\xi a_{it}^\xi + \sum_t \sum_i \sum_{\xi=t}^T FR_{it}^\xi r_{it}^\xi \quad (1)$$

subject to:

$$\sum_i x_{ij}^t = 1, \quad \forall j, t \quad (2)$$

$$\sum_{\tau=1}^t \sum_{\xi=\tau}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) - x_{ij}^t \geq 0, \quad \forall i, j, t \quad (3)$$

$$\sum_{\tau=1}^{t-1} \sum_{\xi=\tau}^{t-1} a_{i\tau}^{\xi} - \sum_{\xi=t}^T r_{it}^{\xi} \geq 0, \quad \forall i, t \quad (4)$$

$$\sum_{t=1}^T \sum_{\xi=t}^T a_{it}^{\xi} \leq 1, \quad \forall i \quad (5)$$

$$\sum_{\tau=1}^t \sum_{\xi=\tau}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) \leq 1, \quad \forall i, t \quad (6)$$

$$Q_i \sum_{\tau=1}^t \sum_{\xi=\tau}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) - \sum_{\tau=1}^t \sum_j d_j^{\tau} x_{ij}^{\tau} \geq 0, \quad \forall i, t \quad (7)$$

$$\begin{aligned} a_{it}^{\xi} &\in \{0, 1\}, \quad \forall i, t, \xi \geq t \\ r_{it}^{\xi} &\in \{0, 1\}, \quad \forall i, t > 1, \xi \geq t \end{aligned} \quad (8)$$

Constraints (2) guarantee that, in every time period, each client's demand is satisfied; constraints (3) assure that, in every time period, a client can only be assigned to facilities that are operational in that time period; constraints (4) and (6) impose that a facility can only be reopened at the beginning of period t if it has already been open earlier and it is not in operation at the beginning of period t and that, in every time period, only one facility can be open in each location; constraints (5) guarantee that a facility can only be opened once during the planning horizon. The model presented considers admissible the situation where a facility is closed even if its capacity has not been totally used. Restriction (7) considers that when a facility is reopened, its maximum capacity will be equal to Q_i plus the remaining capacity the facility had when it was closed. It can be argued that this behavior is not admissible for some kinds of facilities. Thinking, for instance, of sanitary landfills it is easy to imagine that if a sanitary landfill is closed at period t and reopened at period $t + 1$, then its remaining capacity at the end of t can be used. Nevertheless, if the sanitary landfill is reopened several time periods after its closure, its remaining capacity at the end of period t will have been lost (because of all the closing and maintenance operations that need to be performed). The fixed opening and reopening costs of these kind of facilities are generally huge when compared with transportation and handling costs, so it is not expected that a facility with useful remaining capacity will be closed, unless the remaining capacity is insignificant when compared with Q_i . Furthermore, the decision maker is free to consider only the $a_{i\tau}^{\xi}$ and $r_{i\tau}^{\xi}$ variables he/she feels are needed. He/she can, for instance, consider variables such that $\xi - \tau$ is greater than a minimum time interval. For these reasons, the authors feel that the model presented has an acceptable behavior and can be considered useful in the resolution of many real problems, but are aware of the limitations of these capacity restrictions in some situations, especially because the fixed reopening costs do not reflect the time distance between the closure and the reopening periods.

2.1 Formulation of the dual problem

Multiplying constraints (5) and (6) by -1 and associating dual variables v_j^t with constraints (2), w_{ij}^t with constraints (3), u_i^t with constraints (4), ρ_i with constraints (5), π_i^t with constraints (6), λ_i^t with constraints (7) and defining $w_{ij}^t = \max\{0, v_j^t - c_{ij}^t - \sum_{\psi=t}^T d_j^t \lambda_i^\psi\}$, $\forall i, j, t$, the condensed dual of the linear relaxation of DC-DLPOCR can be formulated as:

CDDC-DLPOCR

$$\text{Max} \sum_t \sum_j v_j^t - \sum_i \rho_i - \sum_t \sum_i \pi_i^t$$

subject to:

$$\begin{aligned} & \sum_j \sum_{\tau=t}^{\xi} \max \left\{ 0, v_j^{\tau} - c_{ij}^{\tau} - \sum_{\psi=\tau}^T d_j^{\tau} \lambda_i^{\psi} \right\} \\ & \leq FA_{it}^{\xi} - \sum_{\tau=\xi+1}^T u_i^{\tau} + \rho_i + \sum_{\tau=t}^{\xi} \pi_i^{\tau} - Q_i \sum_{\tau=t}^T \lambda_i^{\tau}, \\ & \forall i, t, \xi = t, \dots, T \end{aligned} \quad (9)$$

$$\begin{aligned} & \sum_j \sum_{\tau=t}^{\xi} \max \left\{ 0, v_j^{\tau} - c_{ij}^{\tau} - \sum_{\psi=\tau}^T d_j^{\tau} \lambda_i^{\psi} \right\} \\ & \leq FR_{it}^{\xi} + u_i^t + \sum_{\tau=t}^{\xi} \pi_i^{\tau} - Q_i \sum_{\tau=t}^T \lambda_i^{\tau}, \\ & \forall i, \quad t > 1, \xi = t, \dots, T \\ & u_i^t, \rho_i, \pi_i^t, \lambda_i^t \geq 0, \quad \forall i, t \end{aligned} \quad (10)$$

2.2 Complementary conditions

Let us define:

$$\begin{aligned} SA_{it}^{\xi} &= FA_{it}^{\xi} - \sum_{\tau=\xi+1}^T u_i^{\tau} + \rho_i + \sum_{\tau=t}^{\xi} \pi_i^{\tau} - \sum_j \sum_{\tau=t}^{\xi} \max \left\{ 0, v_j^{\tau} - c_{ij}^{\tau} - \sum_{\psi=\tau}^T d_j^{\tau} \lambda_i^{\psi} \right\} \\ & - Q_i \sum_{\tau=t}^T \lambda_i^{\tau}, \quad \forall i, t, \xi = t, \dots, T \end{aligned} \quad (11)$$

$$SR_{it}^{\xi} = FR_{it}^{\xi} + u_i^t + \sum_{\tau=t}^{\xi} \pi_i^{\tau} - \sum_j \sum_{\tau=t}^{\xi} \max \left\{ 0, v_j^{\tau} - c_{ij}^{\tau} - \sum_{\psi=\tau}^T d_j^{\tau} \lambda_i^{\psi} \right\} - Q_i \sum_{\tau=t}^T \lambda_i^{\tau}, \quad \forall i, t > 1, \xi = t, \dots, T \quad (12)$$

$$S_{it}^{\xi} = \min \left\{ SA_{it}^{\xi}, SR_{it}^{\xi} \right\}, \quad \forall i, t, \xi = t, \dots, T \quad (13)$$

The following complementary slackness conditions hold if in presence of optimal primal and dual feasible solutions (when there is no duality gap).

$$\left(\sum_{\tau=1}^t \sum_{\xi=t}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) - x_{ij}^t \right) w_{ij}^t = 0, \quad \forall i, j, t \quad (14)$$

$$\left(\sum_{\tau=1}^{t-1} \sum_{\xi=\tau}^{t-1} a_{i\tau}^{\xi} - \sum_{\xi=t}^T r_{it}^{\xi} \right) u_i^t = 0, \quad \forall i, t \quad (15)$$

$$\left(\sum_{t=1}^T \sum_{\xi=t}^T a_{it}^{\xi} - 1 \right) \rho_i = 0, \quad \forall i \quad (16)$$

$$\left(\sum_{\tau=1}^t \sum_{\xi=t}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) - 1 \right) \pi_i^t = 0, \quad \forall i, t \quad (17)$$

$$SA_{it}^{\xi} \cdot a_{it}^{\xi} = 0, \quad \forall i, t, \xi = t, \dots, T \quad (18)$$

$$SR_{it}^{\xi} \cdot r_{it}^{\xi} = 0, \quad \forall i, t > 1, \xi = t, \dots, T \quad (19)$$

$$\left(Q_i \sum_{\tau=1}^t \sum_{\xi=\tau}^T (a_{i\tau}^{\xi} + r_{i\tau}^{\xi}) - \sum_{\tau=1}^t \sum_j d_j^{\tau} x_{ij}^{\tau} \right) \lambda_i^t = 0, \quad \forall i, t \quad (20)$$

3 Primal-dual heuristic

The primal-dual heuristic developed to solve the problem formulated in the previous section builds admissible primal solutions based on admissible dual solutions, trying to force the complementary conditions to be satisfied. The heuristic functioning scheme is the following:

1. Initialisation of dual variables;
2. Dual ascent procedure for dual variables v_j^t ;
3. Primal procedure;
4. Dual adjustment procedure for dual variables ρ_i . If the dual solution is changed go to 2;
5. Repeat the dual-primal adjustment procedure for variables v_j^t until there is no improvement in the dual objective function value;

6. Dual adjustment procedure for dual variables ρ_i . If the dual solution is changed go to 2;
7. Dual ascent procedure for dual variables u_i^t . If the dual solution is changed go to 2;
8. Dual descent procedure for dual variables u_i^t . If the dual solution is changed go to 2;
9. Dual ascent procedure for dual variables λ_i^t . If the dual solution is changed go to 2;
10. Dual descent procedure for dual variables λ_i^t . If the dual solution is changed go to 2;
11. Dual adjustment procedure for variables π_i^t . If the dual solution is changed go to 2.

The heuristic will stop when the optimal solution is found (the pair of primal and dual solutions satisfies all complementary conditions), or when there are no improvements in either primal or dual objective function values. Dual variables are initialised as:

1. $v_j^t = \min_i \{c_{ij}^t\}, \quad \forall j, t; \quad \pi_i^t = 0, \quad \forall i, t;$
2. $u_i^t = \max \left\{ 0, - \min_{\substack{t : FR_{it}^\xi < 0 \\ \xi \geq t}} FR_{it}^\xi \right\} \quad \forall i, t;$
3. $\rho_i = \max \left\{ 0, - \min_t \left(FA_{it}^\xi - \sum_{\tau=\xi+1}^T u_i^\tau \right) \right\}, \quad \forall i, t$

Step 2 of the primal–dual heuristic tries to increase all dual variables $v_j^t, (j, t) \in J^+, J^+ \subset J \times T$. If this procedure is executed in step 2 of the heuristic, then J^+ is the whole set $J \times T$. Whenever this procedure is executed within other procedure, the set J^+ will be defined before the Dual Ascent procedure is called. This procedure is a straightforward adaptation of the one described in Van Roy and Erlenkotter, 1982. The only difference is in the updating step of slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$: each time the value of v_j^t is increased, slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi, \tau \leq t \leq \xi$, have to be updated (its value will be decreased by the same amount the dual variable was increased, if v_j^t is greater than or equal to c_{ij}^t). The assignment costs for period t should be considered equal to $c_{ij}^t + d_j^t \sum_{\tau=t}^T \lambda_i^\tau$.

In most of the capacitated dynamic location problems, after deciding which facilities are open at each time period, the optimal value of the assignment variables can be calculated through the resolution of T transportation problems. In the present problem, the resolution of T transportation problems does not guarantee the calculation of the optimal assignments of clients to facilities, because the available capacity at period t is dependant on the remaining available capacity at the end of period $t - 1$. The

resolution of the following linear programming problem guarantees the calculation of optimal assignments.

PL1

$$\text{Min} \sum_t \sum_i \sum_j c_{ij}^t x_{ij}^t \quad (21)$$

subject to:

$$\sum_{i \in I_t^+} x_{ij}^t = 1, \quad \forall j, t \quad (22)$$

$$Q_i \sum_{\tau=1}^t \sum_{\xi=\tau}^T (a_{i\tau}^\xi + r_{i\tau}^\xi) - \sum_{\tau=1}^t \sum_j d_j^\tau x_{ij}^\tau \geq 0, \quad \forall t, i \in I_t^+ \quad (23)^1$$

$$x_{ij}^t \geq 0, \quad \forall j, t, i \in I_t^+$$

3.1 Dual adjustment procedure for variables ρ_i

If it is possible for a variable ρ_i to decrease its value, the dual objective function value will automatically increase. The value of variable ρ_i can be decreased if $SA_{i\tau}^\xi \neq 0, \forall 1 \leq \tau \leq \xi$. Increasing the value of the dual variable ρ_i , increases all slacks $SA_{i\tau}^\xi$. The change in these slacks allows the increase of some v_j^t that were blocked. However, variables ρ_i have a coefficient of minus one in the dual objective function. Therefore, they should only be increased if the enhancement of variables v_j^t is compensatory. It should be noted that it is worth trying to increase ρ_i only if $SR_{i\tau}^\xi \neq 0$ and $SA_{i\tau}^\xi = 0$. Otherwise, a change in the slack $SA_{i\tau}^\xi$ would not be reflected in dual variables v_j^t .

Dual adjustment procedure for dual variables ρ_i

1. $i \leftarrow 1$;
2. $\Delta\rho_i \leftarrow \min_{\tau \leq \xi} \{SA_{i\tau}^\xi\}$. If $\Delta\rho_i = 0$ then continue. Else go to 7.
3. $\Delta\rho_i = \max\{SR_{i\tau}^\xi : \exists (i, \tau, \xi) \in I_R^+ \text{ with } SA_{i\tau}^\xi = 0 \text{ and } SR_{i\tau}^\xi \neq 0\}$.
4. If $\Delta\rho_i \neq 0$ then $\rho_i \leftarrow \rho_i + \Delta\rho_i$; $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi + \Delta\rho_i, \forall \tau, \xi \geq \tau$. Else go to 8.
5. $J^+ = \{(j, t) : I_j^{t*} = \{i\}, \forall t\}$. Execute the dual ascent procedure for dual variables v_j^t .
 $J^+ = J \times T$. Execute the dual ascent procedure for dual variables v_j^t .
6. $\Delta\rho_i = \min_{\substack{\tau \\ \xi \geq \tau}} SA_{i\tau}^\xi$.
7. $\Delta\rho_i = \min\{\Delta\rho_i, \rho_i\}$. If $\Delta\rho_i \neq 0$ then $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi - \Delta\rho_i, \forall \tau, \xi \geq \tau$; $\rho_i \leftarrow \rho_i - \Delta\rho_i$.
8. If $i = m$ then stop. Else $i \leftarrow i + 1$; go to 2.

¹ Variables $a_{i\tau}^\xi$ and $r_{i\tau}^\xi$ are fixed to one or zero.

3.2 Dual-primal adjustment procedure for variables v_j^t

The dual-primal adjustment procedure for variables v_j^t detects violations of the complementary conditions (14), and decreases the values of some variables v_j^t , allowing other variables v_j^t to increase. This procedure can reduce the number of violations of complementary conditions (14) and, at the same time, can improve the value of the dual objective function.

Consider the following sets:

$$\begin{aligned} I_j^{t*} &= \left\{ i : \exists (\tau, \xi) \text{ with } \tau \leq t \leq \xi \mid (i, \tau, \xi) \in I^* \text{ and } v_j^t \geq c_{ij}^t \right\} \\ I_j^{t+} &= \left\{ i : i \in I_t^+ \text{ and } v_j^t > c_{ij}^t \right\} \\ J_i^{t+} &= \left\{ (j, \tau) : I_j^{t*} = \{i\} \text{ and } (i, \gamma, \xi) \notin I^*, \gamma \leq \xi \leq \tau < t \text{ or } t < \tau \leq \gamma \leq \xi \right\} \end{aligned}$$

The set I_j^{t+} indicates, for each client j , all operating facilities during period t such that v_j^t is greater than the assignment cost c_{ij}^t . A violation of the complementary condition (14) is detected by the existence of, at least, one pair (j, t) such that the number of elements in I_j^{t+} is greater than one. Decreasing the value of a variable v_j^t such that the number of elements in I_j^{t+} is greater than one, means that at least slacks $S_{i\tau}^\xi$, $\tau \leq t \leq \xi$, will be increased for two distinct facilities. This may promote the increase in the dual objective function. The set J_i^{t+} represents all variables v_j^t whose value can be increased with the rise of slack $S_{i\tau}^\xi$, $\tau \leq t \leq \xi$. This procedure is a straightforward adaptation of the one described in [Erlenkotter 1978](#) and [Van Roy and Erlenkotter \(1982\)](#) taking into account the remarks of [Saldanha da Gama and Captivo \(2002\)](#).

3.3 Dual ascent procedure for variables u_i^t

Increasing variables u_i^t , increases slacks SR_{it}^ξ , $\xi \geq t$, but at the same time diminishes slacks $SA_{i\tau}^\xi$, $\tau \leq \xi < t$. If the procedure is able to increase slacks $S_{i\tau}^\xi$ that are blocking variables v_j^t , decreasing $S_{i\tau}^\xi$ that are not blocking any variable v_j^t , then it will be possible to improve the dual objective function value. If there is $SR_{it}^\xi = 0$ and $SA_{it}^\xi \neq 0$, then the increase in u_i^t can be of help. This situation occurs, for instance, when $(i, t, \xi) \in I_A^+$ with $SA_{it}^\xi \neq 0$ and $SR_{it}^\xi = 0$. In this case, SR_{it}^ξ should not increase more than $SA_{it}^\xi - SR_{it}^\xi$, because any further increase will not change the value of S_{it}^ξ . On the other hand, variable u_i^t cannot grow more than the minimum value of $SA_{i\tau}^\xi$, $\forall \tau \leq \xi < t$, so that the dual solution remains admissible. Increasing variable u_i^t can diminish the number of violations of complementary conditions (18). Consider variables u_i^t organized as a sequence of pairs (i, t) .

Dual ascent procedure for dual variables u_i^t

1. Initialise $(i, t) \leftarrow (i, t)_1$; $q \leftarrow 1$.
2. $\xi \leftarrow t$; $\Delta u_i^t \leftarrow 0$; $\delta \leftarrow 0$.
3. If $SR_{it}^\xi = 0$ and $SA_{it}^\xi \neq 0$, then $\Delta u_i^t \leftarrow \max\{\Delta u_i^t, SA_{it}^\xi\}$ and $\delta \leftarrow 1$.
4. If $\xi = T$ go to 5, else $\xi \leftarrow \xi + 1$, go to 3.
5. If $\delta = 0$, go to 7. Else $\Delta u_i^t \leftarrow \min\{\Delta u_i^t, \min_{\tau \leq \gamma < t} SA_{i\tau}^\gamma\}$,
 $SR_{it}^\xi \leftarrow SR_{it}^\xi + \Delta u_i^t, \forall \xi \geq t$.
 $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi - \Delta u_i^t, \forall \tau \leq \xi < t$ and $u_i^t \leftarrow u_i^t + \Delta u_i^t$.
6. $J^+ = \{(j, t) : I_j^* = \{i\}, \forall t\}$. Execute the dual ascent procedure for variables v_j^t .
 $J^+ = J \times T$. Execute the dual ascent procedure for variables v_j^t .
7. If $q = m \times T$ then stop. Else $q \leftarrow q + 1$; $(i, t) \leftarrow (i, t)_q$, go to 2.

3.4 Dual descent procedure for variables u_i^t

Decreasing u_i^t will decrease slacks $SR_{it}^\xi, \xi \geq t$, and increase slacks $SA_{i\tau}^\xi, \tau \leq \xi < t$. To guarantee the admissibility of the dual solution, variable u_i^t can only be decreased if $SR_{it}^\xi > 0, \forall \xi \geq t$. If the procedure is able to increase slacks $S_{i\tau}^\xi$ that are blocking dual variables v_j^t and decrease slacks that do not influence v_j^t values, then it is possible to improve the dual objective function value.

Dual descent procedure for variables u_i^t

1. Initialise $(i, t) \leftarrow (i, t)_1$; $q \leftarrow 1$.
2. If $u_i^t = 0$ go to 6; Otherwise, $\Delta u_i^t \leftarrow 0$; $\delta \leftarrow 0$.
3. If $SR_{it}^\xi > 0, \forall \xi \geq t$, then $\Delta u_i^t \leftarrow \min_{\xi \geq t}\{SR_{it}^\xi\}$ and $\delta \leftarrow 1$.
4. If $\delta = 0$ go to 6. Else $\Delta u_i^t \leftarrow \min\{\Delta u_i^t, u_i^t\}$;
 $SR_{it}^\xi \leftarrow SR_{it}^\xi - \Delta u_i^t, \forall \xi \geq t$.
 $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi + \Delta u_i^t, \forall \tau \leq \xi < t$ and $u_i^t \leftarrow u_i^t - \Delta u_i^t$.
5. $J^+ = \{(j, t) : I_j^* = \{i\}, \forall t\}$. Execute the dual ascent procedure for variables v_j^t .
 $J^+ = J \times T$. Execute the dual ascent procedure for variables v_j^t .
6. If $q = m \times T$ then stop. Else $q \leftarrow q + 1$; $(i, t) \leftarrow (i, t)_q$, go to 2.

3.5 Dual ascent procedure for variables λ_i^t

Variable λ_i^t influences the value of all slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi, \tau \leq t$. Consider the following definitions:

$$\Delta = \max_{\substack{j \in J \\ \tau \leq t}} \left\{ \frac{1}{d_j^\tau} \max \left\{ 0, v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi \right\} \right\};$$

$$J1(t) = \left\{ j \in J : v_j^t - c_{ij}^t - \sum_{\xi=t}^T d_j^\xi \lambda_i^\xi \leq \delta d_j^t \right\}. \quad (24)$$

Proposition 1 If variable λ_i^t is increased by $\delta \in]0, \Delta]$, then slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, $\tau \leq t$, will be changed by:

$$\begin{aligned} \Phi(\delta, \tau, \xi) &= \sum_{s=\tau}^{\min\{\xi, t\}} \left(\sum_{j \in J1(s)} \max \left\{ 0, v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^s \lambda_i^\psi \right\} + \sum_{j \notin J1(s)} \delta d_j^s \right) - \delta Q_i \end{aligned} \quad (25)$$

Proof If λ_i^t is increased by $\delta \in]0, \Delta]$, all sums $\sum_{\psi=s}^T d_j^s \lambda_i^\psi$, with $s \leq t$, will be increased by $d_j^s \delta$. These sums influence the values of all slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$. If $t > \xi$ then all sums with $\tau \leq s \leq \xi$ have to be taken into account. If $t \leq \xi$, then only sums with $\tau \leq s \leq t$ will change (sums with $s > t$ will not be altered). For each s , $\tau \leq s \leq \min\{\xi, t\}$, $v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^s \lambda_i^\psi$ with $j \in J1(s)$ will become less than or equal to zero (and the corresponding w_{ij}^s variable will be equal to zero). For all $j \notin J1(s)$, variables w_{ij}^s will be decreased by $d_j^s \delta$. Dual variable λ_i^t influences all slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, $\tau \leq t$, not only due to sums $\sum_{\psi=s}^T d_j^s \lambda_i^\psi$, with $\tau \leq s \leq t$, but also due to the sum $Q_i \sum_{\psi=\tau}^T \lambda_i^\psi$. This sum will be increased by δQ_i . Therefore, it can be concluded that the total change in slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, $\tau \leq t$, due to a change δ in dual variable λ_i^t is given by $\Phi(\delta, \tau, \xi)$. \square

As can be seen by expression (25), slacks influenced by the increase in the dual variable will have different behaviors: some can be increased while others can be decreased.

Proposition 2 Consider that λ_i^t is increased by δ' , with $\delta' > \Delta$, being the resulting slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$. It is possible to find $\delta \in]0, \Delta]$ such that if λ_i^t is increased by δ instead of δ' , the resulting values of all slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$, will be greater than or equal to $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$.

The proof follows directly from proposition 1 and the definition of Δ . Proposition 1 motivates the following dual ascent procedure for variables λ_i^t .

Dual ascent procedures for variables λ_i^t

1. $t \leftarrow 1$;
2. $i \leftarrow 1$; $\delta' \leftarrow +\infty$;
3. $\delta \leftarrow \max_{\substack{j \in J \\ \tau \leq t}} \left\{ \frac{1}{d_j^\tau} \max \left\{ 0, v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi \right\} \right\};$
 $\frac{1}{d_j^\tau} \max \{0, v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi\} < \delta'$
4. If $\delta = 0$, then go to 9.

5. Compute $J1(t)$ as in (24). If $\exists SA_{i\tau}^\xi$ or $SR_{i\tau}^\xi$, $\tau \leq t$, such that $SA_{i\tau}^\xi + \Phi(\delta, \tau, \xi) < 0$ or $SR_{i\tau}^\xi + \Phi(\delta, \tau, \xi) < 0$ go to 6. Else go to 7.
6. If $\delta' = 0$, then go to 9. Else $\delta' \leftarrow \delta$. Go to 4.
7. $\lambda_i^t \leftarrow \lambda_i^t + \delta$; $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi + \Phi(\delta, \tau, \xi)$ and $SR_{i\tau}^\xi \leftarrow SR_{i\tau}^\xi + \Phi(\delta, \tau, \xi)$, $\forall \tau \leq t$.
8. Execute the dual ascent procedure for variables v_j^t .
9. $i \leftarrow i + 1$; if $i > m$ then go to 10. Else go to 3.
10. $t \leftarrow t + 1$; if $t > T$ then stop. Else go to 2.

3.6 Dual descent procedure for variables λ_i^t

A decrease in the dual variable λ_i^t will increase all values $v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi$, $\forall \tau \leq t$.

Proposition 3 If λ_i^t is decreased by δ , with:

$$0 < \delta \leq \min_{\substack{\tau \leq t \\ j \in J}} \left\{ -\frac{v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi}{d_j^\tau} \right\}, \quad (26)$$

$$v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi < 0$$

then all slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$, will be changed by:

$$\Omega(\delta, \tau, \xi) = \delta \left(Q_i - \sum_{\psi=\tau}^{\min\{\xi, t\}} \sum_{j \in J} d_j^\psi \right). \quad (27)$$

$$v_j^\psi - c_{ij}^\psi - \sum_{s=\psi}^T d_j^s \lambda_i^s \geq 0$$

Proof If λ_i^t is decreased by δ , all values $v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi$, $s \leq t$, will be increased by δd_j^s . To guarantee that $v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi < 0$ will remain less than or equal to zero:

$$v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi + \delta d_j^s \leq 0 \Leftrightarrow \delta \leq -\frac{v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi}{d_j^s}.$$

Therefore, the upper limit defined by (26) guarantees that for all j and s such that $v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi < 0$, this value will continue smaller than zero. For each slack $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$, all values $v_j^s - c_{ij}^s - \sum_{\psi=s}^T d_j^\psi \lambda_i^\psi \geq 0$, with $s \leq \min\{\xi, t\}$, will be increased by δd_j^s . Each of these slacks is also influenced by the decrease δQ_i in sum $Q_i \sum_{\psi=\tau}^T \lambda_i^\psi$. Therefore $\Omega(\delta, \tau, \xi)$ expresses the change occurred in slacks $SA_{i\tau}^\xi$ and $SR_{i\tau}^\xi$, with $\tau \leq t$, due to a decrease δ in dual variable λ_i^t . \square

Proposition 3 motivates the following dual descent procedure for variables λ_i^t .

Dual descent procedure for variables λ_i^t

1. $t \leftarrow 1$;
2. $i \leftarrow 1$;
3. $\delta \leftarrow \min \left\{ \lambda_i^t, \min_{\substack{\tau \leq t \\ j \in J}} \left\{ -\frac{v_j^\tau - c_{ij}^\tau - \sum_{\xi=\tau}^T d_j^\xi \lambda_i^\xi}{d_j^\tau} \right\} \right\}$; If $\delta = 0$, then go to 7.
4. If $SA_{i\tau}^\xi + \Omega(\delta, \tau, \xi) < 0$ or $SR_{i\tau}^\xi + \Omega(\delta, \tau, \xi) < 0$, for some $\tau \leq t$, then:

$$\delta \leftarrow \min_{\substack{\tau \leq t \\ \Omega(\delta, \tau, \xi) < 0}} \left\{ -\frac{SA_{i\tau}^\xi}{\Omega(\delta, \tau, \xi)/\delta}, -\frac{SR_{i\tau}^\xi}{\Omega(\delta, \tau, \xi)/\delta} \right\}.$$
5. If $\delta = 0$ go to 7. Else $SA_{i\tau}^\xi \leftarrow SA_{i\tau}^\xi + \Omega(\delta, \tau, \xi)$ and $SR_{i\tau}^\xi \leftarrow SR_{i\tau}^\xi + \Omega(\delta, \tau, \xi)$, $\forall \tau \leq t$. $\lambda_i^t \leftarrow \lambda_i^t + \delta$.
6. Execute the dual ascent procedure for variables v_j^t .
7. $i \leftarrow i + 1$; if $i > m$ then go to 8. Else go to 3.
8. $t \leftarrow t + 1$; if $t > T$ then stop. Else go to 2.

3.7 Dual adjustment procedure for variables π_i^t

Increasing the value of π_i^t will increase slacks $S_{i\tau}^\xi$, $\tau \leq t \leq \xi$. If there are slacks $S_{i\tau}^\xi$, $\tau \leq t \leq \xi$ that are blocking dual variables v_j^t , then it is possible to improve the value of the dual objective function. However it is only worth to increase π_i^t if the change in dual variables v_j^t compensates the loss of π_i^t in the objective function value (the variable π_i^t has a coefficient of minus one). If the procedure is able to diminish the value of π_i^t , maintaining the dual solution feasibility, then there is an immediate improvement in the dual objective function value.

Consider variables π_i^t organized as a sequence of pairs (i, t) , and M a large positive number.

Dual adjustment procedure for variables π_i^t

1. Initialise $(i, t) \leftarrow (i, t)_1$; $q \leftarrow 1$.
2. $\Delta\pi_i^t = \min_{\tau \leq t \leq \xi} S_{i\tau}^\xi$. If $\Delta\pi_i^t \neq 0$, then go to 6. Else $\Delta\pi_i^t \leftarrow M$.
3. $S_{i\tau}^\xi \leftarrow S_{i\tau}^\xi + \Delta\pi_i^t$, $\forall \tau \leq t \leq \xi$; $\pi_i^t = \pi_i^t + \Delta\pi_i^t$.
4. $J^+ = \{(j, t) : I_j^{t*} = \{i\}, \forall t\}$. Execute the dual ascent procedure for variables v_j^t .
 $J^+ = J \times T$. Execute the dual ascent procedure for variables v_j^t .
5. $\Delta\pi_i^t = \min_{\tau \leq t \leq \xi} S_{i\tau}^\xi$.

6. $\Delta\pi_i^t = \min\{\Delta\pi_i^t, \pi_i^t\}$. If $\Delta\pi_i^t \neq 0$ then $S_{i\tau}^\xi \leftarrow S_{i\tau}^\xi - \Delta\pi_i^t, \forall \tau \leq t \leq \xi$ and $\pi_i^t = \pi_i^t - \Delta\pi_i^t$.
7. If $q = m \times T$ then stop. Else $q \leftarrow q + 1; (i, t) \leftarrow (i, t)_{q,}$ go to 2.

3.8 Primal procedure

The primal procedure, here developed, guarantees the calculation of a primal admissible solution, if one exists for DC-PLDOCR. It begins by calculating a solution for the uncapacitated problem. When it is necessary to open more services during a period t , the procedure calculates the cost of opening facilities not in operation during that time period, but also the cost of opening or reopening facilities before period t . Every time a facility is (re) open, its capacity is increased. Consider the following notation:

$$I^* = \{(i, \tau, \xi) : S_{i\tau}^\xi = 0\}$$

$$I_t^* = \{i : (i, \tau, \xi) \in I^* \text{ and } \tau \leq t \leq \xi\}$$

$$I_t^+ = \{i : \text{facility } i \text{ is open during period } t\}$$

$$I_A^+ = \{(i, \tau, \xi) : a_{i\tau}^\xi = 1\}$$

$$I_R^+ = \{(i, \tau, \xi) : r_{i\tau}^\xi = 1\}$$

$$h_i^t = \text{smallest cost incurred by opening a facility } i \notin I_t^+ \text{ during period } t.$$

$$p_i^t = \text{smallest cost incurred by reopening a facility } i \in I_t^+ \text{ at the beginning of a period } t' < t.$$

$$\text{Cap}_i^t = \text{Maximum capacity of facility } i \text{ at the beginning of time period } t.$$

DC-DLPOCR primal procedure

1. $I_A^+ = I_R^+ = \emptyset, I_t^+ = \emptyset, \forall t$. Build sets I^* and I_t^* . Num = 0;
2. For $t = 1, \dots, T$, include in set I_t^+ all facilities i such that $\exists j : v_j^t \geq c_{ij}^t$ and $v_j^t < c_{i'j}^t, \forall i' \neq i$.
3. For each client j such that $v_j^t < c_{ij}^t, \forall i \in I_t^+$, include in set I_t^+ facility i such that $c_{ij}^t = \min_{v_j^t \geq c_{i'j}^t} c_{i'j}^t$. Num = Num + 1. If Num = 1 then $I_A^+ = I_R^+ = \emptyset, I_t^* = I_t^+$ and $I_t^+ = \emptyset, \forall t$, go to 2. Else continue.
4. Build sets I_A^+ and I_R^+ . Update I_t^+ . For $t = 1, \dots, T$, assign each client j to facility $i' \in I_t^+$ such that $c_{i'j}^t = \min_{i \in I} \{c_{ij}^t\}$.
5. Test complementary slackness conditions.
6. Solve problem PL1 optimally using a general solver. If PL1 has no admissible solutions, go to 7. Else stop.
7. $t \leftarrow 1, \text{Cap}_i^1 \leftarrow Q_i, \forall i \in I_1^+$ and $\text{Cap}_i^1 \leftarrow 0, \forall i \notin I_1^+$.
8. $D \leftarrow \sum_j d_j^1; C \leftarrow \sum_{i \in I_1^+} \text{Cap}_i^1$. If $D \leq C$ then go to 13.
9. Calculate $h_i^t, \forall i \notin I_t^+$ and $p_i^t, \forall i \in I_t^+, h_i^t \leftarrow +\infty, \forall i \in I_t^+$ and $p_i^t \leftarrow +\infty, \forall i \notin I_t^+$.
10. Choose i' such that $\min \{h_{i'}^t, p_{i'}^t\} = \min \{h_i^t, p_i^t\}$ where $h_i^t = \min_{i \in I} \{h_i^t\}$ and $p_i^t = \min_{i \in I} \{p_i^t\}$.
11. Rebuild sets $I_A^+, I_R^+, I_t^+, \forall t$ and recalculate $\text{Cap}_i^t, \forall i$, and C according to the choice made in 10.



Fig. 1 represents facility i functioning time periods

12. If $D > C$ then go to 9. Else continue.
13. Solve one transportation problem considering as sources the set J of clients (with supplies d_j^t), as destinations the set I_t^+ (with demands Cap_i^t), and unit transportation costs given by c_{ij}^t/d_j^t . Consider the values of the transportation variables designated by x_{ij}^t .
14. $\text{Cap}_i^t \leftarrow \text{Cap}_i^t - \sum_{j \in J} x_{ij}^t, \forall i \in I_t^+$.
15. $t \leftarrow t + 1$; if $t > T$, then go to 6. Else continue.
16. If $\exists(i, t, \xi) \in I_A^+ \cup I_R^+$, then $\text{Cap}_i^t \leftarrow \text{Cap}_i^{t-1} + Q_i$. Else $\text{Cap}_i^t \leftarrow \text{Cap}_i^{t-1}$. Go to 8.

In the primal procedure, steps 4 and 5 require special attention. As a matter of fact, building sets I_A^+ and I_R^+ is much more complicated than building set I^+ as described in Dynaloc [Van Roy and Erlenkotter \(1982\)](#) taking into account the remarks of [Saldanha da Gama and Captivo \(2002\)](#). If, for a facility $i \in I_t^+$, $S_{i\tau}^\xi = 0$, $\tau \leq t \leq \xi$ for more than one pair (τ, ξ) , the choice of which variable to include in set I_A^+ or I_R^+ is not trivial. For each facility i , these procedures include in I_A^+ or I_R^+ variables guaranteeing that facility i will be open at least during periods t such that $i \in I_t^+$, and that satisfy constraints (4)–(6).

Considering time periods a, b, c, d (Fig. 1) defined formally as ²

$$b = \max \left\{ 0, \max_{t' < t} \{t' : i \in I_{t'}^+\} \right\}; a = t' \text{ such that } (i, t', b) \in I_A^+ \cup I_R^+;$$

$$c = \min \left\{ T + 1, \min_{t' > t} \{t' : i \in I_{t'}^+\} \right\}; d = t' \text{ such that } (i, c, t') \in I_A^+ \cup I_R^+;$$

the calculation of h_i^t is made as follows:

Calculation of h_i^t for $i \notin I_t^+$

1. If $b = 0$ and $c = T + 1$ then $F_i^t \leftarrow \min \{FA_{i\tau}^\xi : 1 \leq \tau \leq t \leq \xi \leq T\}$. Stop.
2. If $b = 0$ and $c \leq T$ then
 $F_i^t \leftarrow \min \left\{ \min \{FA_{i\tau}^\xi - FA_{ic}^d + FR_{ic}^d : 1 \leq \tau \leq t \leq \xi < c\}, \right.$
 $\left. \min \{FA_{i\tau}^d - FA_{ic}^d : 1 \leq \tau \leq t\} \right\}$. Stop.
3. If $b > 0$ and $c = T + 1$ then go to 4. Else go to 7.
4. If $(i, a, b) \in I_A^+$ then go to 5. Else go to 6.
5. $F_i^t \leftarrow \min \{ \min \{FA_{ia}^\xi - FA_{ia}^b : t \leq \xi \leq T\}, \min \{FR_{i\tau}^\xi : b < \tau \leq t \leq \xi \leq T\} \}$. Stop.

² Time period b represents the time period before and nearest to t such that facility i is operating. Time period c represents the time period after and nearest to t such that facility i is operating.

6. $F_i^t \leftarrow \min\{\min\{FR_{ia}^\xi - FR_{ia}^b : t \leq \xi \leq T\}, \min\{FR_{i\tau}^\xi : b < \tau \leq t \leq \xi \leq T\}\}$, . Stop.
7. If $(i, a, b) \in I_A^+$ then go to 8. Else go to 9.
8. $F_i^t \leftarrow \min\{FA_{ia}^d - FA_{ia}^b - FR_{ic}^d, \min\{FR_{i\tau}^\xi, b < \tau \leq t \leq \xi < c\}, \min\{FA_{ia}^\xi - FA_{ia}^b, t \leq \xi < c\}, \min\{FR_{i\tau}^d - FR_{ic}^d, b < \tau \leq t\}\}$, . Stop.
9. $F_i^t \leftarrow \min\{FR_{ia}^d - FR_{ia}^b - FR_{ic}^d, \min\{FR_{i\tau}^\xi, b < \tau \leq t \leq \xi < c\}, \min\{FR_{ia}^\xi - FR_{ia}^b, t \leq \xi < c\}, \min\{FR_{i\tau}^d - FR_{ic}^d, b < \tau \leq t\}\}$, ; Stop.

The possibility of changing the value of variables a_{ia}^b or r_{ia}^b is considered only if facility i has remaining capacity greater than zero at the end of time period b (otherwise, even if the facility was operational during time period t , it would not increase the total available capacity).

If a service is already open during time period t , there is the possibility of increasing its available capacity by (re) opening the facility before time period t . This can be achieved either by splitting variables $a_{i\tau}^\xi$ or $r_{i\tau}^\xi$, with $\tau \leq t$, that are considered equal to one in the present primal solution or by considering new variables $a_{i\tau'}^\xi$ or $r_{i\tau'}^\xi$ such that $i \notin I_{\tau'}^+$, for $\tau \leq \tau' \leq \xi < t$. The calculation of p_i^t takes all these possibilities into account.

Calculation of p_i^t for $i \in I_t^+$

1. $p_i^t \leftarrow \min \left\{ +\infty, \min_{\substack{(i, \tau, \xi) \in I_A^+ \\ \tau \leq t \\ \xi \leq t}} \left\{ FA_{i\tau}^\xi + FR_{i\xi+1}^\xi - FA_{i\tau}^\xi \right\}, \min_{\substack{(i, \tau, \xi) \in I_R^+ \\ \tau \leq t \\ \xi \leq t}} \left\{ FR_{i\tau}^\xi + FR_{i\xi+1}^\xi - FR_{i\tau}^\xi \right\} \right\}.$
2. $t1 \leftarrow 1$;
3. If $i \in I_{t1}^+$ go to 6. Else continue.
4. $b = \max\{0, \max_{t' < t1} \{t' : i \in I_{t'}^+\}\}$; $c = \min\{t, \min_{t' > t1} \{t' : i \in I_{t'}^+\}\}$;
5. If $b = 0$, there exists $(i, a, d) \in I_A^+$. Then
 $p_i^t \leftarrow \min\{p_i^t, \min_{b < \tau \leq \xi < c} \{FA_{i\tau}^\xi\} + FR_{ia}^d - FA_{ia}^d\}$. Else $p_i^t \leftarrow \min\{p_i^t, \min_{b < \tau \leq \xi < c} \{FR_{i\tau}^\xi\}\}$.
6. $t1 \leftarrow t1 + 1$; If $t1 = t$ then go to 7. Else go to 3.
7. $p_i^t \leftarrow \frac{p_i^t}{Q_i} \lceil \frac{\phi_i}{Q_i} \rceil$, where $\phi_i = \begin{cases} D - C, & \text{if } C + Q_i < D \\ Q_i, & \text{otherwise} \end{cases}$. Stop.

4 Computational tests

4.1 Description of the computational experiments

The primal-dual heuristic was tested with a set of randomly generated problems. The following values for m , n and T ($n > m$) were considered and, for each combination, 5 instances were generated (total of 270 problems):

n	25	50	100	200	500
m	5	10	20	50	
T	5	10	20		

The data for the test problems were generated according to the following procedure:

1. Random generation of (x, y) coordinates in the plane of the $m + n$ nodes of the network, according to a uniform distribution and considering a 500×500 square.
2. Random creation of arcs between the network nodes, with a probability of 75%.
3. Creation of arcs (not created in step 2) between nodes such that the Euclidean distance from one another is less than 50, with probability of 80%.
4. For the first period, the costs associated with arcs are randomly generated according to a uniform distribution, in the interval $[100, 1100]$. For $t > 1$, the cost associated to the arc in period t is equal to the cost in period $t - 1$ plus a changing factor randomly generated corresponding to a variation between -10% and $+10\%$.
5. For each time period, calculation of the shortest path between each client and each facility, using the Floyd-Warshall algorithm.
6. For each facility i and period t , consider $t_{end} = t, \dots, T$. For $t_{end} = t$, the fixed costs for variables $a_{it}^{t_{end}}$ and $r_{it}^{t_{end}}$ are randomly generated according to a uniform distribution in the interval $[500, 3,500]$. For $t_{end} > t$, a factor between 0% and 10% , that represents an increase in the fixed cost for $t_{end} - 1$, is randomly generated.
7. The maximum capacities and the clients demands in each time period are randomly generated as described in [Saldanha da Gama \(2002\)](#).

All experiments were carried out in a Pentium 4, 1.80 Ghz, running under Windows 2000 operating system, with a maximum of 2,000 MB of virtual memory and 260 Mb of Ram. The heuristic was programmed using C-language and Microsoft Visual C++ compiler. The performance of the algorithm was compared with the performance of CPLEX, version 7.0.

CPLEX terminates without calculating the optimal solution whenever more than 2,100,000,000 nodes of the branch and bound tree are explored, or when the number of simplex iterations in a node exceeds 2,100,000,000, or when there is not enough memory to read the problem or when the execution time exceeds 200,000 s.

After the execution of the primal-dual heuristic, a local search procedure was executed. Let:

SOL_S = set of solutions constituting the k -neighborhood of solution S ;

Z_S = primal objective function value considering solution S .

Definition 1 An admissible solution S' is said to be in the k - neighborhood of the admissible solution S if and only if S' differs from S by the insertion or removal of at most k functioning continuous time periods to a service i .

The local search procedure can be described as follows:

Local search procedure

1. $k \leftarrow 1$. S = current primal solution.
2. Calculate $S^+ \in SOL_S$ such that $Z_{S^+} = \min_{S' \in SOL_S} \{Z_{S'}\}$
3. If $Z_{S^+} < Z_S$, then $S \leftarrow S^+$ and go to 2. Else continue.
4. $k \leftarrow k + 1$. If $k > T$ then stop. Else go to 2.

We also tested the performance of a lagrangean heuristic procedure that uses the subgradient optimization method applied to the lagrangean relaxation obtained by relaxing, in a lagrangean way, the capacity restrictions. An uncapacitated dynamic location problem is obtained that is optimized using the heuristics described in [Dias et al. \(2007\)](#). Then a primal procedure similar to the one described in this paper is used to find an admissible solution.

4.2 Computational results

Table 1 shows the quality of the primal solutions found by the heuristic. It shows the results obtained when the dual variables are initialised as described in Sect. 3 (columns 4–6). It also shows average results of the quality of the primal solutions obtained by the primal-dual heuristic after the execution of the local search procedure around the best solution found by the heuristic (columns 7–9). In the following columns the results presented were obtained when the dual variables are initialised by solving a linear programming problem, as described in [Saldanha da Gama \(2002\)](#). Table 2 shows the results obtained with the lagrangean heuristic described in the end of the previous section. The tables show the worst, the best and the average value of the deviations of the final primal solution found from the best known lower bound on the optimal value. This lower bound is equal to the optimum value for all problems CPLEX was able to solve. For all the others, this lower bound is given by the best dual solution found by the primal-dual heuristic. The values shown are calculated as $(Z - Z_{LB})/Z_{LB}$, where Z is the objective function value of the final primal solution found and Z_{LB} is the value of the lower bound. In Tables 1 and 2 there are some values greater than 100%. This happens for sets of problems that CPLEX was unable to solve and was not even capable of solving the linear relaxation. This means that the best lower bound known is the one given by the primal-dual heuristics. As can be seen in Table 3, that shows the quality of the dual solution calculated by the heuristics, the quality of this lower bound is very poor. The quality of the lower bound is calculated as $(Z^* - Z_{LB})/Z^*$, where Z^* represents the best upper bound known. That is why these values greater than 100% appear in Table 1. Table 4 shows the computational times spent by the heuristics and by CPLEX. CPLEX is unable to solve one of the five problems with (T, n, m) equal to (20,100,20) and is capable of solving only one of the five problems with (T, n, m) equal to (20,200,20). The symbol ‘—’ is used in Table 3 for all cases where CPLEX was not capable of solving any of the five problems.

Table 1 Quality of the primal solution in percentage (primal-dual heuristic)

<i>T</i>	<i>n</i>	<i>m</i>	Heuristic			Heuristic + local search			Heuristic with Initialisation using a LP			Heuristic with Initialisation using a LP + local search		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
5	25	5	0.22	1.17	3.47	0.00	0.12	0.62	0.24	2.21	4.95	0.00	1.26	4.88
5	25	10	1.21	2.01	4.17	0.89	1.59	3.45	0.77	2.28	3.85	0.68	1.94	3.56
5	25	20	1.46	2.72	3.89	1.40	2.12	3.26	1.06	2.53	3.87	0.41	2.02	3.51
5	50	5	0.11	0.96	1.30	0.02	0.69	1.21	0.80	3.05	6.30	0.00	1.56	4.17
5	50	10	1.31	2.93	4.68	1.30	2.43	3.40	1.46	2.22	3.62	0.74	1.51	1.98
5	50	20	1.42	2.72	3.86	0.74	2.21	3.86	1.31	3.20	5.81	0.91	2.43	3.99
5	100	5	0.42	1.75	4.65	0.10	1.38	3.86	0.00	2.38	4.57	0.00	2.10	4.46
5	100	10	1.00	1.46	2.05	0.72	1.16	2.05	0.73	1.52	2.25	0.44	1.09	1.79
5	100	20	1.40	2.44	3.49	1.40	1.99	2.89	0.87	2.03	3.24	0.63	1.59	3.24
5	100	50	1.71	3.23	4.40	1.34	2.86	3.59	1.70	3.18	3.78	1.70	2.69	3.17
5	200	5	0.03	1.45	2.82	0.00	0.77	2.02	0.03	1.38	2.82	0.01	1.11	2.12
5	200	10	1.22	1.91	2.80	0.99	1.56	2.05	1.30	2.13	3.11	0.99	1.84	2.89
5	200	20	1.76	2.61	3.88	1.41	2.21	3.88	0.97	2.16	3.69	0.68	1.71	2.56
5	200	50	3.14	4.07	5.10	2.31	3.54	5.10	2.82	4.07	4.88	2.80	3.82	4.88
5	500	5	0.00	0.66	1.38	0.00	0.55	1.18	0.00	1.00	2.84	0.00	0.72	1.76
5	500	10	0.42	1.13	2.58	0.36	1.02	2.21	0.46	1.82	2.78	0.39	1.58	2.44
5	500	20	0.78	2.32	3.44	0.70	1.79	3.13	1.11	1.94	2.93	0.99	1.55	2.21
5	500	50	2.92	3.64	5.13	2.46	3.43	5.13	3.06	3.97	4.91	2.32	2.90	3.33
10	25	5	0.76	1.32	2.35	0.09	0.78	1.17	0.83	2.07	5.70	0.54	1.75	5.52
10	25	10	1.53	2.62	3.92	0.85	2.03	3.92	0.81	2.26	3.65	0.81	1.64	2.70
10	25	20	2.20	3.52	4.69	1.46	2.47	3.73	2.98	3.97	5.07	1.33	2.49	3.88
10	50	5	0.54	1.82	4.43	0.54	1.53	2.99	0.06	2.05	6.04	0.01	1.98	5.86
10	50	10	1.79	2.02	2.57	1.08	1.72	2.57	0.76	2.12	3.99	0.52	1.39	1.92
10	50	20	2.96	3.24	3.81	1.90	2.53	3.81	2.60	3.12	3.62	2.25	2.78	3.22
10	100	5	0.16	0.70	1.26	0.01	0.42	0.99	0.26	1.27	2.57	0.14	0.68	2.00
10	100	10	1.19	1.90	3.00	0.29	1.35	3.00	1.80	2.12	2.43	1.33	1.68	2.18
10	100	20	1.92	2.45	2.91	1.15	1.95	2.91	1.75	2.39	3.00	1.21	1.99	2.40
10	100	50	3.14	4.11	4.98	2.25	3.42	4.19	3.30	4.25	4.95	2.65	3.42	4.31
10	200	5	0.23	1.52	2.26	0.01	1.11	2.19	0.23	1.31	2.14	0.23	1.13	1.51
10	200	10	1.10	1.94	3.03	0.40	1.53	2.52	1.62	2.83	5.19	1.32	2.24	3.50
10	200	20	2.05	2.94	3.53	1.22	1.73	2.38	1.94	3.07	3.62	1.94	2.57	3.14
10	200	50	3.60	3.70	3.85	2.97	3.48	3.85	3.14	3.49	3.82	2.18	2.57	3.01
10	500	5	0.14	0.75	1.36	0.01	0.58	1.33	0.41	0.88	1.19	0.41	0.76	0.99
10	500	10	0.73	1.61	2.38	0.65	1.31	1.63	1.12	1.77	2.75	1.01	1.45	2.54
10	500	20	1.80	2.26	2.83	1.43	1.66	2.05	1.68	2.38	3.18	1.17	2.07	2.62
10	500	50	3.07	3.78	4.32	2.47	3.08	3.96	3.04	3.73	4.57	2.58	3.31	4.57
20	25	5	1.45	3.09	4.51	1.36	2.13	3.29	1.32	3.64	5.24	1.21	2.37	2.77
20	25	10	2.63	3.15	3.90	2.04	2.67	3.11	2.67	3.40	3.91	1.89	2.42	3.00

Table 1 *Continued*

<i>T</i>	<i>n</i>	<i>m</i>	Heuristic			Heuristic + local search			Heuristic with Initialisation using a LP			Heuristic with Initialisation using a LP + local search		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
20	25	20	3.96	5.13	5.97	2.78	3.94	5.97	4.14	6.02	7.94	2.51	3.47	4.51
20	50	5	1.47	2.55	4.34	0.50	1.77	3.40	0.67	2.32	4.64	0.28	1.49	3.06
20	50	10	1.35	1.98	2.77	0.85	1.48	2.21	1.34	2.69	5.30	1.02	2.11	4.52
20	50	20	4.17	4.77	5.48	3.99	4.62	5.48	3.92	4.48	5.31	2.08	3.07	3.92
20	100	5	0.93	2.34	3.74	0.93	2.06	3.31	0.66	2.45	4.87	0.58	1.84	2.85
20	100	10	2.63	3.11	3.65	2.06	2.63	3.20	2.66	3.20	4.50	1.62	2.56	3.07
20	100	20	2.99	3.94	4.50	2.52	3.18	4.40	3.28	3.72	4.07	2.31	2.63	3.28
20	100	50	109.91	128.20	137.60	108.56	127.02	136.43	120.99	130.55	156.65	110.39	131.50	139.25
20	200	5	1.79	2.13	2.49	1.51	1.88	2.40	2.36	2.89	3.25	1.89	2.38	2.95
20	200	10	1.10	1.91	2.70	0.96	1.69	2.21	2.61	2.91	3.10	2.25	2.58	2.76
20	200	20	2.86	3.39	4.26	1.88	2.75	3.55	3.02	4.23	5.02	2.42	3.12	3.77
20	200	50	115.41	132.04	151.36	113.99	130.83	150.07	120.25	136.96	165.30	119.25	128.59	162.20
20	500	5	1.58	2.85	3.95	1.19	2.28	3.56	1.75	3.12	4.03	1.49	2.98	3.63
20	500	10	2.43	3.04	4.50	1.42	2.02	2.28	2.23	4.15	5.11	2.23	3.51	4.25
20	500	20	3.65	4.37	7.29	2.44	3.86	4.24	3.98	5.12	7.43	3.18	4.98	6.69
20	500	50	118.87	143.93	165.74	116.27	141.29	162.08	123.60	152.60	163.97	122.55	151.07	161.87

Table 2 Quality of the primal solution in percentage (lagrangean heuristics)

<i>T</i>	<i>n</i>	<i>m</i>	Lagrangean heuristic			Lagrangean heuristic + local search		
			Best	Average	Worst	Best	Average	Worst
5	25	5	0.00	3.77	9.44	0.00	2.38	6.05
5	25	10	0.91	5.59	7.58	0.86	4.35	6.98
5	25	20	3.06	4.97	7.71	2.09	4.08	7.17
5	50	5	0.00	1.58	4.68	0.00	1.13	2.56
5	50	10	1.48	4.67	8.34	0.95	2.80	4.00
5	50	20	3.19	5.49	9.73	1.52	4.51	8.58
5	100	5	0.97	3.42	4.73	0.97	3.23	4.64
5	100	10	2.62	6.05	13.04	1.88	4.51	10.47
5	100	20	3.81	5.68	8.54	3.22	4.60	6.66
5	100	50	3.66	5.47	8.04	3.03	4.65	7.58
5	200	5	2.08	3.09	4.16	0.00	1.93	3.50
5	200	10	3.36	4.64	6.69	2.33	3.82	6.23
5	200	20	4.20	5.73	8.20	3.03	3.98	4.89
5	200	50	5.19	6.28	7.40	4.03	5.11	6.15
5	500	5	0.00	1.54	3.12	0.00	1.02	1.81

Table 2 *Continued*

<i>T</i>	<i>n</i>	<i>m</i>	Lagrangean Heuristic			Lagrangean heuristic + local search		
			Best	Average	Worst	Best	Average	Worst
5	500	10	0.57	3.85	6.53	0.44	2.66	4.96
5	500	20	2.87	4.23	5.96	1.66	3.49	5.35
5	500	50	4.66	6.03	7.04	3.89	4.56	5.39
10	25	5	4.27	8.40	11.44	4.12	5.16	6.38
10	25	10	4.73	7.89	10.78	3.13	4.95	6.67
10	25	20	4.53	7.77	10.70	2.39	3.32	3.90
10	50	5	4.63	7.81	15.96	3.23	6.35	15.61
10	50	10	3.42	11.54	30.00	0.77	7.67	20.89
10	50	20	5.92	7.84	10.15	3.28	5.40	9.46
10	100	5	4.95	9.25	22.99	2.08	5.57	15.02
10	100	10	3.45	6.51	13.56	2.60	4.63	9.72
10	100	20	5.32	8.89	13.61	2.20	5.82	10.35
10	100	50	5.31	6.61	8.23	3.74	4.52	5.17
10	200	5	4.76	7.17	11.77	4.22	6.18	8.80
10	200	10	3.24	6.12	8.45	2.45	4.39	6.32
10	200	20	5.74	10.21	14.36	2.86	6.78	11.60
10	200	50	5.02	7.15	7.84	4.02	5.05	5.37
10	500	5	0.20	0.95	1.57	0.17	0.89	1.18
10	500	10	1.89	2.35	3.86	1.32	2.15	3.28
10	500	20	2.88	3.14	3.90	2.73	3.10	3.71
10	500	50	5.62	6.04	7.32	4.21	5.12	5.42
20	25	5	2.32	3.86	5.75	1.85	2.89	5.52
20	25	10	3.91	4.52	4.96	3.17	3.24	3.47
20	25	20	5.59	6.25	7.04	4.42	5.07	5.28
20	50	5	1.24	3.57	6.29	1.11	2.48	5.09
20	50	10	2.22	2.89	4.15	1.91	2.75	3.28
20	50	20	6.50	6.75	7.24	5.65	6.21	6.52
20	100	5	1.38	2.84	3.56	1.22	2.45	2.88
20	100	10	4.50	4.81	5.92	3.60	4.21	4.44
20	100	20	4.75	5.94	8.34	3.56	5.45	6.67
20	100	50	135.26	142.50	158.58	128.96	139.54	149.66
20	200	5	2.80	3.68	5.28	2.10	3.12	4.43
20	200	10	1.72	2.98	3.64	1.63	2.46	2.87
20	200	20	5.23	5.98	6.64	4.19	5.34	5.71
20	200	50	125.21	142.35	166.54	122.15	134.77	163.25
20	500	5	2.75	3.39	5.40	2.31	2.96	4.38
20	500	10	3.84	4.21	4.44	3.34	3.68	3.86
20	500	20	7.04	7.56	9.03	4.93	5.38	6.77
20	500	50	125.80	151.80	164.85	123.54	148.99	162.80

Table 3 Quality of the dual solution in percentage

T	n	m	Heuristic			Heuristic with LP initialisation			Lagrangean heuristic		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
5	25	5	15.37	24.61	34.78	6.42	13.58	21.55	0.66	24.40	42.61
5	25	10	16.85	25.93	30.60	7.66	11.17	14.31	1.42	31.82	43.69
5	25	20	27.06	27.77	28.48	9.27	12.90	17.34	42.85	44.12	45.66
5	50	5	13.81	25.93	42.56	7.66	13.60	27.78	2.54	20.83	47.52
5	50	10	27.48	29.08	30.57	8.92	12.72	17.22	31.77	35.96	39.07
5	50	20	22.80	27.60	32.87	7.68	12.32	19.68	32.86	37.10	41.30
5	100	5	19.64	25.90	34.22	8.32	11.73	16.22	18.01	28.97	40.68
5	100	10	21.12	29.14	39.52	7.31	13.23	22.07	29.15	36.49	46.93
5	100	20	27.21	30.08	32.28	9.03	11.55	13.29	37.44	38.80	40.44
5	100	50	28.81	30.91	32.39	13.56	14.32	15.57	40.22	43.43	48.50
5	200	5	22.77	32.69	37.77	14.90	18.61	21.87	21.08	32.03	40.31
5	200	10	28.37	34.25	42.09	8.85	16.13	28.39	27.84	37.55	48.64
5	200	20	26.51	29.87	36.00	8.33	13.54	19.86	31.80	37.04	41.14
5	200	50	31.12	35.29	37.98	15.36	18.13	21.23	42.39	45.33	46.95
5	500	5	26.08	34.32	42.55	12.59	17.94	22.17	2.13	21.94	35.85
5	500	10	30.13	36.73	46.93	15.34	18.28	24.36	28.29	32.75	36.39
5	500	20	31.60	35.71	42.46	14.89	18.31	22.70	27.89	35.15	43.98
5	500	50	33.76	36.10	39.87	15.11	18.08	21.07	42.01	44.13	47.48
10	25	5	29.32	35.06	39.98	10.01	16.01	20.72	33.14	40.42	44.43
10	25	10	31.63	36.93	46.23	12.34	16.44	22.67	38.27	43.31	52.12
10	25	20	34.91	38.45	41.15	17.27	20.16	22.99	45.37	47.50	49.62
10	50	5	24.70	34.44	49.43	10.09	16.10	25.01	29.34	38.33	52.85
10	50	10	31.51	36.58	43.69	11.09	16.45	21.88	37.35	42.07	48.68
10	50	20	37.27	42.21	44.35	13.34	20.36	24.41	44.01	49.28	51.52
10	100	5	30.74	37.89	45.61	13.74	19.52	24.73	21.96	39.04	48.12
10	100	10	35.83	38.59	41.84	13.74	18.92	22.22	25.89	39.41	47.86
10	100	20	34.74	37.95	41.87	15.46	17.54	19.53	40.81	44.46	48.97
10	100	50	41.19	42.06	43.98	20.76	21.59	23.10	49.17	50.44	52.51
10	200	5	30.11	34.12	38.48	13.77	16.94	22.79	33.26	36.37	39.21
10	200	10	35.48	39.41	44.36	17.69	34.27	91.55	35.72	40.81	44.93
10	200	20	35.92	38.85	41.43	15.44	18.38	20.72	42.75	44.20	46.19
10	200	50	38.66	40.58	42.15	16.31	19.56	22.78	48.87	53.78	64.89
10	500	5	37.95	40.84	44.88	19.52	22.44	29.85	31.48	40.21	42.85
10	500	10	35.29	42.90	51.35	16.46	22.82	32.07	45.96	46.89	47.98
10	500	20	37.18	42.14	48.31	18.10	21.91	25.09	38.15	40.82	41.76
10	500	50	42.55	45.88	48.33	21.60	24.94	27.56	37.28	42.17	44.69
20	25	5	36.26	40.15	45.39	19.09	20.54	22.52	36.07	41.89	44.06
20	25	10	41.03	43.95	46.20	20.46	22.50	24.32	27.60	35.25	41.21
20	25	20	46.98	48.71	50.55	21.36	24.40	26.54	31.43	40.01	42.26

Table 3 *Continued*

<i>T</i>	<i>n</i>	<i>m</i>	Heuristic			Heuristic with LP initialisation			Lagrangean heuristic		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
20	50	5	33.73	43.10	50.21	15.99	21.93	28.18	35.25	41.89	44.88
20	50	10	40.97	46.34	52.90	18.49	24.33	29.68	38.97	40.56	43.80
20	50	20	45.08	48.14	50.65	22.16	23.70	26.19	28.65	38.10	42.83
20	100	5	33.05	39.38	42.43	14.23	18.96	21.16	43.89	45.87	46.58
20	100	10	42.60	48.22	53.90	20.62	23.81	29.20	40.69	42.54	44.58
20	100	20	45.05	49.20	52.02	20.36	25.01	28.68	38.74	39.85	43.77
20	100	50	52.05	55.85	57.70	32.54	36.45	42.26	26.52	32.58	46.82
20	200	5	38.53	41.71	46.95	21.52	33.54	38.95	42.62	43.12	44.21
20	200	10	39.87	48.77	57.88	37.59	39.78	48.48	40.90	42.03	43.51
20	200	20	46.73	48.99	50.08	42.48	45.26	48.89	32.11	36.56	42.31
20	200	50	47.80	49.22	51.80	43.54	47.95	49.25	37.02	39.60	46.25
20	500	5	35.69	42.57	49.88	33.98	38.96	45.87	32.47	35.98	43.25
20	500	10	37.55	42.69	51.49	34.58	39.48	48.54	41.50	43.13	44.62
20	500	20	34.57	43.54	56.00	33.48	38.45	54.47	33.35	38.77	44.43
20	500	50	42.69	44.52	58.10	43.02	46.15	53.87	37.46	38.99	39.83

4.3 Conclusions

The analysis of the computational results allows the following conclusions:

1. The primal-dual heuristic developed is capable of calculating good quality solutions for the problem.
2. Initialising the dual variables by solving a linear programming problem decreases the quality of the best primal solution found.
3. The lagrangean heuristic calculates, on average, solutions that are worse than the primal-dual heuristics. This is a different result from the one obtained with the other capacitated problems studied by the authors.
4. The local search procedure can increase significantly the quality of the best primal solution found with a significant increase in the computational times.
5. The computational time spent by CPLEX is, on average, more than 10 times greater than the time spent by the heuristics. It is also interesting to note that most of the times CPLEX finishes without calculating the optimal solution to the problem. In average it calculates primal solutions that are 0.02% distant from the best lower bound known.
6. The heuristics presented are not capable of calculating good lower bounds. As can be seen in Table 2, the lower bounds calculated are of very poor quality.
7. Only 0.03% of the linear relaxations of the problems generated have an optimal integer solution.

Table 4 Computational times in Seconds

T	n	m	Heuristic			Heuristic + local search			Heuristic with LP initialisation			Heuristic with LP initialisation + local search		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
5	25	5	0.20	0.42	0.88	0.33	0.55	1.00	0.03	0.14	0.34	0.13	0.24	0.38
5	25	10	1.34	1.86	3.00	2.00	2.46	3.50	0.20	0.98	1.72	0.53	1.54	2.28
5	25	20	2.80	3.55	4.27	3.42	8.14	11.09	0.50	4.49	13.97	3.56	9.21	18.91
5	50	5	0.45	0.71	1.06	0.64	0.96	1.23	0.08	0.15	0.33	0.23	0.37	0.47
5	50	10	1.89	3.11	6.77	2.52	4.51	7.49	0.80	1.83	4.78	2.31	3.64	7.23
5	50	20	5.50	9.29	15.97	6.94	14.63	24.31	0.53	7.72	19.42	8.41	17.01	31.21
5	100	5	1.44	3.23	4.41	1.80	3.77	4.64	0.38	1.78	4.03	0.81	2.15	4.27
5	100	10	4.24	9.63	14.16	8.27	13.32	20.63	2.52	8.08	13.20	6.03	12.40	21.05
5	100	20	19.36	26.46	32.41	29.41	45.70	69.36	4.84	45.04	102.86	8.19	69.85	140.74
5	100	50	262.63	458.47	796.91	291.85	782.83	1091.03	25.42	349.80	513.02	438.70	733.44	1044.17
5	200	5	6.06	8.51	10.58	7.14	9.68	12.55	0.95	2.62	5.17	2.45	3.64	5.81
5	200	10	11.13	29.67	61.47	21.99	43.25	85.06	3.50	11.57	28.53	15.20	21.72	31.06
5	200	20	117.21	180.56	239.43	217.35	296.89	465.51	5.61	80.62	170.69	92.55	168.56	277.67
5	200	50	720.38	1913.01	3493.57	1905.17	3762.35	6137.44	126.39	1071.32	4112.93	252.78	1845.70	4245.37
5	500	5	28.81	73.23	153.93	34.63	80.17	157.83	4.16	43.20	152.43	8.44	52.00	164.04
5	500	10	163.58	257.08	399.35	194.10	301.51	426.36	9.50	76.67	127.63	75.78	108.19	163.18
5	500	20	380.54	1158.09	2700.24	625.45	1783.19	3673.38	120.27	444.72	875.58	707.55	1104.20	1685.69
5	500	50	13159.91	21361.88	35254.99	19572.96	30073.71	37640.63	1931.89	9657.81	34525.64	10459.74	22350.64	47733.16
10	25	5	0.91	1.48	2.27	1.53	2.63	3.27	0.17	0.81	1.58	0.80	1.92	3.44

Table 4 Continued

T	n	m	Heuristic			Heuristic + local search			Heuristic with LP initialisation			Heuristic with LP initialisation + local search		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
10	25	10	2.56	5.00	5.88	6.77	13.04	16.27	0.69	3.17	6.92	5.80	9.90	15.80
10	25	20	10.71	23.97	37.78	67.11	88.02	101.80	1.88	8.71	33.30	61.89	75.57	97.35
10	50	5	2.09	3.19	4.91	3.27	4.63	5.77	0.42	2.29	4.80	1.80	3.66	6.53
10	50	10	6.17	15.03	24.19	9.41	25.71	51.92	0.44	7.94	18.17	8.89	23.45	30.67
10	50	20	25.77	41.04	51.30	62.50	176.65	303.95	32.36	61.58	109.52	80.05	124.32	169.96
10	100	5	5.67	9.96	22.74	9.92	14.21	30.08	1.02	6.10	20.36	5.89	10.79	24.36
10	100	10	12.70	44.33	110.25	43.67	94.60	121.52	4.00	16.41	37.81	40.61	75.78	125.25
10	100	20	162.77	278.30	524.31	195.49	623.43	966.03	23.69	252.62	505.69	290.62	568.79	834.03
10	100	50	1151.59	2450.31	4898.91	3167.88	10805.39	17058.68	183.63	616.71	2110.29	6236.89	7902.28	9580.65
10	200	5	29.88	48.02	75.72	44.28	65.14	110.35	4.92	20.26	43.95	25.80	34.00	50.53
10	200	10	144.10	338.53	713.32	343.09	508.26	891.98	13.74	77.97	277.12	151.13	264.57	312.74
10	200	20	790.11	1710.94	2785.07	2904.90	4500.50	6598.19	122.02	528.48	1143.71	542.86	1785.06	2782.21
10	200	50	2698.40	7670.13	18453.68	15486.25	17706.59	58466.82	259.87	4946.40	19655.89	0.00	23820.40	47021.97
10	500	5	127.68	355.15	685.68	188.68	426.35	713.16	12.83	212.42	418.70	98.03	285.72	445.98
10	500	10	631.33	1157.69	1916.48	1325.34	2056.20	3180.71	76.82	491.51	1039.58	641.18	1134.25	2214.31
10	500	20	9947.82	16868.06	28665.21	23422.00	32148.47	39152.14	646.60	2535.50	4657.12	5599.65	9902.68	14757.58
10	500	50	55877.62	87158.30	114482.84	121300.18	341679.19	439949.13	17890.18	75416.58	198013.84	43864.48	203211.04	355459.95

Table 4 Continued

T	n	m	Heuristic			Heuristic + local search			Heuristic with LP initialisation			Heuristic with LP initialisation + local search		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
20	25	5	2.78	4.38	8.03	8.22	13.12	18.22	0.72	5.73	20.00	9.11	15.20	27.11
20	25	10	9.91	17.39	29.69	22.13	78.27	140.18	4.67	13.49	35.02	81.05	110.63	166.44
20	25	20	82.00	130.74	205.35	132.52	969.14	1402.61	15.16	72.76	160.07	737.85	999.77	1258.79
20	50	5	4.97	9.14	16.20	21.14	34.25	50.45	1.31	7.99	14.16	23.30	27.70	36.53
20	50	10	37.00	65.28	101.27	214.52	247.59	296.79	10.38	28.98	52.35	167.22	202.75	233.18
20	50	20	212.32	305.11	416.69	320.90	606.40	1390.17	41.61	102.97	153.30	242.15	1614.30	2699.95
20	100	5	11.66	42.20	77.72	71.85	89.46	113.54	4.30	19.33	56.05	27.56	79.09	131.49
20	100	10	86.47	278.47	471.61	567.86	893.76	1198.43	31.24	161.60	421.20	438.26	799.69	1214.46
20	100	20	1450.75	2752.20	4235.43	1868.81	9267.28	15822.16	200.12	1246.58	3065.46	1793.96	6798.73	11137.45
20	100	50	13708.00	21059.52	35063.17	15663.27	75838.17	165274.26	10281.00	26545.14	34361.91	10763.78	50408.33	158986.56
20	200	5	105.68	162.71	228.45	297.81	323.16	388.70	84.54	152.25	194.18	254.89	394.24	451.68
20	200	10	603.57	1054.88	1686.79	1137.32	2318.56	4018.93	513.03	1125.29	1653.05	1789.51	3986.43	5785.68
20	200	20	10263.45	18159.94	22563.39	16863.95	40523.63	55927.49	4105.38	12052.29	22789.03	12120.15	28521.85	45122.28
20	200	50	18888.80	26370.56	56299.04	32089.78	42896.57	65498.17	6611.08	32407.13	50106.14	16250.03	82518.15	99210.16
20	500	5	633.27	2145.54	3400.96	996.22	3164.43	4956.48	506.62	2131.80	2550.72	800.46	6485.75	9157.09
20	500	10	3799.64	12084.54	20405.78	5379.59	25832.22	34695.38	2849.73	13262.10	18365.20	23225.29	44010.65	77152.20
20	500	20	24869.55	51304.14	71663.04	50123.08	118529.91	139381.63	10445.21	52285.88	75246.19	93589.07	158890.22	320097.28
20	500	50	110637.68	198468.35	226676.01	218340.32	225739.35	227589.15	54212.46	210932.96	255114.33	169413.95	245868.22	265157.35

Table 4 Continued

T	n	m	Lagrangean heuristic			Lagrangean heuristic + local search			CPLEX		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
5	25	5	1.53	2.49	5.08	3.06	4.97	6.11	0.19	2.48	7.19
5	25	10	2.98	5.29	13.34	20.81	24.24	28.95	3.34	12.76	28.78
5	25	20	6.41	6.64	6.91	127.41	143.22	162.07	46.63	276.56	852.86
5	50	5	2.98	6.38	12.00	5.09	9.29	13.84	5.52	15.71	42.08
5	50	10	6.39	6.76	7.23	35.66	55.04	71.75	29.78	54.62	113.39
5	50	20	12.02	12.99	15.09	140.96	274.35	358.17	81.33	2081.09	7447.09
5	100	5	5.56	6.74	8.34	9.70	12.06	14.00	7.17	11.97	21.75
5	100	10	11.52	12.83	14.25	50.55	85.51	111.89	70.51	209.63	619.99
5	100	20	25.94	27.60	29.81	455.69	623.93	856.45	218.34	701.74	1532.67
5	100	50	73.69	78.63	88.68	6758.69	7690.21	9363.03	9182.86	31019.28	59177.34
5	200	5	12.81	14.18	15.24	24.95	36.07	44.33	62.45	121.59	214.34
5	200	10	24.35	27.36	30.03	109.64	160.96	227.79	94.84	454.05	951.91
5	200	20	55.39	62.49	69.55	1204.09	1581.21	2116.01	972.22	5333.65	10604.09
5	200	50	190.79	210.14	256.18	16947.59	21096.12	25722.68	5344.91	127499.79	200098.61
5	500	5	11.54	33.38	40.58	53.46	73.78	91.08	162.48	366.43	868.34
5	500	10	88.08	92.97	97.69	244.71	375.52	525.92	847.89	1682.37	3734.39
5	500	20	209.73	228.93	245.77	2634.49	3806.99	4765.82	3912.63	19078.13	65750.22
5	500	50	673.01	698.55	743.24	48027.18	72579.75	85677.87	20031.30	200064.78	200126.44
10	25	5	4.74	5.13	5.81	19.05	32.07	50.75	3.03	12.26	31.75

Table 4 Continued

T	n	m	Lagrangian heuristic			Lagrangian heuristic + local search			CPLEX		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
10	25	10	9.59	10.30	11.22	215.79	317.89	398.45	30.45	118.87	355.52
10	25	20	21.33	22.43	22.97	1896.23	2386.58	2731.78	205.14	9983.48	25885.67
10	50	5	9.19	9.76	10.50	30.24	54.74	69.82	6.23	23.48	52.23
10	50	10	17.88	20.04	22.50	372.72	508.45	686.77	47.92	260.59	747.17
10	50	20	41.41	44.41	48.38	3523.69	4825.56	6280.89	406.52	10888.38	20202.53
10	100	5	19.80	21.65	23.53	86.52	144.65	224.59	36.48	230.03	517.28
10	100	10	40.31	43.33	46.25	695.91	940.62	1222.46	223.14	548.67	845.94
10	100	20	85.43	93.96	99.16	8165.39	9837.16	14093.44	2218.50	50962.52	200029.78
10	100	50	275.45	322.53	341.81	6328.70	38952.52	167314.85	121567.22	172208.70	200202.58
10	200	5	39.99	41.39	46.81	157.58	235.82	279.13	68.84	1112.95	3901.81
10	200	10	87.08	100.55	105.18	1681.84	2186.68	3062.90	1186.14	5574.84	10370.64
10	200	20	211.21	225.56	241.62	16712.11	23580.19	29049.70	6939.69	103152.79	200120.47
10	200	50	553.89	756.96	856.53	23578.11	56244.52	77055.15	200192.84	200277.92	200428.22
10	500	5	64.44	580.55	2521.21	447.92	18545.54	85219.55	519.70	1866.89	3208.50
10	500	10	502.37	2586.22	3976.91	2929.54	10425.55	12510.82	12906.09	89244.19	200227.27
10	500	20	6828.09	18683.53	26647.39	25584.79	45235.24	83380.34	116841.61	179875.60	200409.99
10	500	50	148916.44	150080.57	152871.61	200416.81	203762.28	208348.72	—	—	—
20	25	5	2.34	33.84	132.98	41.62	120.24	153.17	25.95	98.94	209.48
20	25	10	16.36	187.78	293.14	370.32	526.21	940.40	482.13	1281.91	2556.92
20	25	20	2.86	67.95	86.73	3371.25	5365.87	7112.17	3760.39	62446.97	163523.95
20	50	5	2.86	52.54	115.80	106.45	176.41	206.41	74.34	252.07	531.64

Table 4 Continued

T	n	m	Lagrangean heuristic			Lagrangean heuristic + local search			CPLEX		
			Best	Average	Worst	Best	Average	Worst	Best	Average	Worst
20	50	10	68.33	138.11	168.06	764.05	906.54	1317.47	396.89	8609.62	32815.39
20	50	20	240.11	255.61	261.98	1106.37	8545.42	15254.69	13779.34	87671.28	200092.05
20	100	5	29.91	123.78	469.26	125.94	421.58	742.91	179.94	510.24	951.38
20	100	10	229.71	936.41	3488.07	2002.43	5854.55	6861.70	1066.59	4422.62	10658.67
20	100	20	1018.50	7010.42	8534.66	8196.62	22612.36	62926.60	27390.05	105007.92	200471.97
20	100	50	51824.02	66985.45	99792.16	49179.70	154652.55	198274.06	—	—	—
20	200	5	526.15	848.32	1053.87	1164.59	2175.12	2551.99	1029.44	1219.48	1776.34
20	200	10	3075.75	5862.25	14863.60	8176.27	22786.54	32689.11	9815.08	66700.98	178804.48
20	200	20	8491.28	32542.24	81564.55	55376.97	97286.55	254940.86	210511.41	210511.41	210511.41
20	200	50	56634.58	99215.88	248584.02	74246.41	112503.24	260537.48	—	—	—
20	500	5	579.67	7512.25	16680.60	3657.29	34255.55	51737.57	—	—	—
20	500	10	16336.91	85453.24	147860.42	106116.33	126950.69	135909.29	—	—	—
20	500	20	54678.66	157000.44	182658.54	127608.46	168651.25	199136.33	—	—	—
20	500	50	117410.51	156421.56	166228.48	174052.32	193571.55	219449.75	—	—	—

5 Final comments and future work directions

This work was motivated by the good results obtained with the computational tests performed with the primal-dual heuristic developed for the uncapacitated dynamic location problem (Dias et al. 2007). The computational tests already performed with the heuristic presented in this paper indicate that the primal solutions found by the heuristic are of good quality. The authors have also developed similar heuristics for multi-level capacitated and uncapacitated problems, and also for capacitated problems when the facilities can have different capacities.

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